How Deterministic are Good-For-Games Automata?*

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Abstract -

In good for games (GFG) automata, it is possible to resolve nondeterminism in a way that only depends on the past and still accepts all the words in the language. The motivation for GFG automata comes from their adequacy for games and synthesis, wherein general nondeterminism is inappropriate. We continue the ongoing effort of studying the power of nondeterminism in GFG automata. Initial indications have hinted that every GFG automaton embodies a deterministic one. Today we know that this is not the case, and in fact GFG automata may be exponentially more succinct than deterministic ones.

We focus on the *typeness* question, namely the question of whether a GFG automaton with a certain acceptance condition has an equivalent GFG automaton with a weaker acceptance condition on the same structure. Beyond the theoretical interest in studying typeness, its existence implies efficient translations among different acceptance conditions. This practical issue is of special interest in the context of games, where the Büchi and co-Büchi conditions admit memoryless strategies for both players. Typeness is known to hold for deterministic automata and not to hold for general nondeterministic automata.

We show that GFG automata enjoy the benefits of typeness, similarly to the case of deterministic automata. In particular, when Rabin or Streett GFG automata have equivalent Büchi or co-Büchi GFG automata, respectively, then such equivalent automata can be defined on a substructure of the original automata. Using our typeness results, we further study the place of GFG automata in between deterministic and nondeterministic ones. Specifically, considering automata complementation, we show that GFG automata lean toward nondeterministic ones, admitting an exponential state blow-up in the complementation of a Streett automaton into a Rabin automaton, as opposed to the constant blow-up in the deterministic case.

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1 Introduction

Nondeterminism is a prime notion in theoretical computer science. It allows a computing machine to examine, in a concurrent manner, all its possible runs on a certain input. For

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automata on finite words, nondeterminism does not increase the expressive power, yet it leads to an exponential succinctness [15]. For automata on infinite words, nondeterminism may increase the expressive power and also leads to an exponential succinctness. For example, nondeterministic Büchi automata are strictly more expressive than their deterministic counterpart [11]. In the automata-theoretic approach to formal verification, we use automata on infinite words in order to model systems and their specifications. In particular, temporal logic formulas are translated to nondeterministic word automata [19]. In some applications, such as model checking, algorithms can proceed on the nondeterministic automaton, whereas in other applications, such as synthesis and control, they cannot. There, the advantages of nondeterminism are lost, and the algorithms involve a complicated determinization construction [16] or acrobatics for circumventing determinization [10]. Essentially, the inherent difficulty of using nondeterminism in synthesis lies in the fact that each guess of the nondeterministic automaton should accommodate all possible futures.

Some nondeterministic automata are, however, good for games: in these automata it is possible to resolve the nondeterminism in a way that only depends on the past while still accepting all the words in the language. This notion, of good for games (GFG) automata was first introduced in [4]. Formally, a nondeterministic automaton \mathcal{A} over an alphabet Σ is GFG if there is a strategy g that maps each finite word $u \in \Sigma^+$ to the transition to be taken after u is read; and following g results in accepting all the words in the language of \mathcal{A} . Note that a state g of \mathcal{A} may be reachable via different words, and g may suggest different transitions from g after different words are read. Still, g depends only on the past, namely on the word read so far. Obviously, there exist GFG automata: deterministic ones, or nondeterministic ones that are determinizable by pruning (DetByP); that is, ones that just add transitions on top of a deterministic automaton. In fact, the GFG automata constructed in [4] are DetByP.²

Our work continues a series of works that have studied GFG automata: their expressive power, succinctness, and constructions for them, where the key challenge is to understand the power of nondeterminism in GFG automata. Let us first survey the results known so far. In terms of expressive power, it is shown in [8, 14] that GFG automata with an acceptance condition of type γ (e.g., Büchi) are as expressive as deterministic γ automata.³ Thus, as far as expressiveness is concerned, GFG automata behave like deterministic ones. The picture in terms of succinctness is diverse. For automata on finite words, GFG automata are always DetByP [8, 12]. For automata on infinite words, in particular Büchi and co-Büchi automata⁴, GFG automata need not be DetByP [2]. Moreover, the best known determinization construction of GFG Büchi automata is quadratic, whereas determinization of GFG co-Büchi automata has an exponential blow-up lower bound [6]. Thus, in terms of succinctness, GFG automata on infinite words are more succinct (possibly even exponentially) than deterministic ones.

For deterministic automata, where Büchi and co-Büchi automata are less expressive than Rabin and Streett ones, researchers have come up with the notion of an automaton being type [5]. Consider a deterministic automaton \mathcal{A} with acceptance condition of type

¹ GFGness is also used in [3] in the framework of cost functions under the name "history-determinism".

² As explained in [4], the fact that the GFG automata constructed there are DetByP does not contradict their usefulness in practice, as their transition relation is simpler than the one of the embodied deterministic automaton and it can be defined symbolically.

³ The results in [8, 14] are given by means of tree automata for derived languages, yet, by [2], the results hold also for GFG automata.

⁴ See Section 2.1 for the full definition of the various acceptance conditions.

 γ and assume that \mathcal{A} recognizes a language that can be recognized by some deterministic automaton with an acceptance condition of type β that is weaker than γ . When deterministic γ automata are β -type, it is guaranteed that a deterministic β -automaton for the language of \mathcal{A} can be defined on top of the structure of \mathcal{A} .

For example, deterministic Rabin automata being Büchi-type [5] means that if a deterministic Rabin automaton \mathcal{A} recognizes a language that can be recognized by a deterministic Büchi automaton, then \mathcal{A} has an equivalent deterministic Büchi automaton on the same structure.

Thus, the basic motivation of typeness is to allow simplifications of the acceptance conditions of the considered automata without complicating their structure. Applications of this notion are much wider [5]. In particular, in the context of games, the Büchi and co-Büchi conditions admit memoryless strategies for both players, which is not the case for the Rabin and Streett conditions [18]. Thus, the study of typeness in the context of GFG automata addresses also the question of simplifying the memory requirements of the players. In addition, as we elaborate in Section 7, it leads to new and non-trivial bounds on the blow-up of transformations between GFG automata and their complementation.

Recall that deterministic Rabin automata are Büchi-type. Dually, deterministic Streett automata are co-Büchi-type. Typeness can be defined also with respect to nondeterministic automata, yet it crucially depends on the fact that the automaton is deterministic. Indeed, nondeterministic Rabin are not Büchi-type. Even with the co-Büchi acceptance condition, where nondeterministic co-Büchi automata recognize only a subset of the ω -regular languages, nondeterministic Streett automata are not co-Büchi-type [7].

We first show that typeness is strongly related with determinism even when slightly relaxing the typeness notion to require the existence of an equivalent automaton on a substructure of the original automaton, instead of on the exact original structure, and even when we restrict attention to an unambiguous automaton, namely one that has a single accepting run on each word in its language. We describe an unambiguous parity automaton \mathcal{A} , such that its language is recognized by a deterministic Büchi automaton, yet it is impossible to define a Büchi acceptance condition on top of a substructure of \mathcal{A} . We also point to a dual result in [7], with respect to the co-Büchi condition, and observe that it applies also to the relaxed typeness notion.

We then show that for GFG automata, typeness, in its relaxed form, does hold. Notice that once considering GFG automata with no redundant transitions, which we call *tight*, the two typeness notions coincide. Obviously, all GFG automata can be tightened by removal of redundant transitions (Lemma 4). In particular, we show that the typeness picture in GFG automata coincides with the one in deterministic automata: Rabin GFG automata are Büchi type, Streett GFG automata are co-Büchi type, and all GFG automata are type with respect to the weak acceptance condition. Unlike the deterministic case, however, the Rabin case is not a simple dualization of the Streett case; it is much harder to prove and it requires a stronger notion of tightness.

We continue with using our typeness results for further studying the place of GFG automata in between deterministic and nondeterministic ones. We start with showing that all GFG automata that recognize languages that can be defined by deterministic weak automata are DetByP. This generalizes similar results about safe and co-safe languages [7]. We then show that all unambiguous GFG automata are also DetByP. Considering complementation, GFG automata lie in between the deterministic and nondeterministic settings—the complementation of a Büchi automaton into a co-Büchi automaton is polynomial, as is the case with deterministic automata, while the complementation of a co-Büchi automaton into a Büchi

automaton as well as the complementation of a Streett automaton into a Rabin automaton is exponential, as opposed to the constant blow-up in the deterministic case. We conclude with proving a doubly-exponential lower bound for the translation of LTL into GFG automata, as is the case with deterministic automata.

The paper is structured as follows. In Section 2 we provide the relevant notions about languages and GFG automata. Section 3 contains examples showing that typeness does not hold for the case of unambiguous automata. The next three sections, Sections 4, 5, and 6, provide the main positive results of this work: co-Büchi typeness for GFG-Streett; Büchi typeness for GFG-Rabin; and weak typeness for GFG-Büchi and GFG-co-Büchi, respectively. Finally, in Section 7 we continue to study the power of nondeterminism in GFG automata, looking into automata complementation and translations of LTL formulas to GFG automata. Due to lack of space, some full proofs are missing, and can be found in the full version, in the authors' URLs.

2 Preliminaries

2.1 Automata

An automaton on infinite words is a tuple $\mathcal{A} = \langle \Sigma, Q, Q_0, \delta, \alpha \rangle$, where Σ is an input alphabet, Q is a finite set of states, $Q_0 \subseteq Q$ is a set of initial states, $\delta \colon Q \times \Sigma \to 2^Q$ is a transition function that maps a state and a letter to a set of possible successors, and α is an acceptance condition. The first four elements, namely $\langle \Sigma, Q, \delta, Q_0 \rangle$, are the automaton's structure. We consider here the $B\ddot{u}chi$, $co\text{-}B\ddot{u}chi$, parity, Rabin, and $\mathbf{Streett}$ acceptance conditions. (The weak condition is defined in Section 6.) In B\"uchi, and co-B\"uchi conditions, $\alpha \subseteq Q$ is a set of states. In a parity condition, $\alpha \colon Q \to \{0, \dots, k\}$ is a function mapping each state to its priority. In a Rabin and Streett conditions, $\alpha \subseteq 2^{2^Q \times 2^Q}$ is a set of pairs of sets of states. The index of a Rabin or Streett condition is the number of pairs in it. For a state q of \mathcal{A} , we denote by \mathcal{A}^q the automaton that is derived from \mathcal{A} by changing the set of initial states to $\{q\}$. A transition of \mathcal{A} is a triple $\langle q, a, q' \rangle$ such that $q' \in \delta(q, a)$. We extend δ to sets of states and to finite words in the expected way. Thus, for a set $S \subseteq Q$, a letter $a \in \Sigma$, and a finite word $u \in \Sigma^*$, we have that $\delta(S, \epsilon) = S$, $\delta(S, a) = \bigcup_{q \in S} \delta(q, a)$, and $\delta(S, u \cdot a) = \delta(\delta(S, u), a)$. Then, we denote by $\mathcal{A}(u)$ the set of states that \mathcal{A} may reach when reading u. Thus, $\mathcal{A}(u) = \delta(Q_0, u)$.

Since the set of initial states need not be a singleton and the transition function may specify several successors for each state and letter, the automaton \mathcal{A} may be nondeterministic. If $|Q_0| = 1$ and $|\delta(q, a)| \leq 1$ for every $q \in Q$ and $a \in \Sigma$, then \mathcal{A} is deterministic.

Given an input word $w = a_1 \cdot a_2 \cdots$ in Σ^{ω} , a run of \mathcal{A} on w is an infinite sequence $r = r_0, r_1, r_2, \ldots \in Q^{\omega}$ such that $r_0 \in Q_0$ and for every $i \geq 0$, we have $r_{i+1} \in \delta(r_i, a_{i+1})$; i.e., the run starts in the initial state and obeys the transition function. For a run r, let $\inf(r)$ denote the set of states that r visits infinitely often. That is, $\inf(r) = \{q \in Q \mid \text{for infinitely many } i \geq 0$, we have $r_i = q\}$.

A set of states S satisfies an acceptance condition α (or is accepting) iff

- $S \cap \alpha \neq \emptyset$, for a Büchi condition.
- $S \cap \alpha = \emptyset$, for a co-Büchi condition.
- $= \min_{q \in \inf(r)} \{\alpha(q)\}\$ is even, for a parity condition.
- There exists $\langle E, F \rangle \in \alpha$, such that $S \cap E = \emptyset$ and $S \cap F \neq \emptyset$ for a Rabin condition.
- For all $\langle E, F \rangle \in \alpha$, we have $S \cap E = \emptyset$ or $S \cap F \neq \emptyset$ for a Streett condition.

Notice that Büchi and co-Büchi are dual, and so are Rabin and Streett. Also note that the Büchi and co-Büchi conditions are special cases of parity, which is a special case of Rabin and Streett. In the latter conditions, we refer to the sets E and F as the "bad" and "good"

sets, respectively. Finally, note that a Rabin pair may have an empty E component, while an empty F component makes the pair redundant (and dually for Streett).

A run r is accepting if $\inf(r)$ satisfies α . An automaton \mathcal{A} accepts an input word w iff there exists an accepting run of \mathcal{A} on w. The language of \mathcal{A} , denoted by $L(\mathcal{A})$, is the set of all words in Σ^{ω} that \mathcal{A} accepts. A nondeterministic automaton \mathcal{A} is unambiguous if for every word $w \in L(\mathcal{A})$, there is a single accepting run of \mathcal{A} on w. Thus, while \mathcal{A} is nondeterministic and may have many runs on each input word, it has only a single accepting run on words in its language.

We denote the different automata types by three-letter acronyms in the set $\{D, N\} \times \{B, C, P, R, S\} \times \{W\}$. The first letter stands for the branching mode of the automaton (deterministic or nondeterministic); the second for the acceptance-condition type (Büchi, co-Büchi, parity, Rabin, or Streett); and the third indicates that we consider automata on words. For Rabin and Streett automata, we sometimes also indicate the index of the automaton. In this way, for example, NBW are nondeterministic Büchi word automata, and DRW[1] are deterministic Rabin automata with index 1.

For two automata \mathcal{A} and \mathcal{A}' , we say that \mathcal{A} and \mathcal{A}' are equivalent if $L(\mathcal{A}) = L(\mathcal{A}')$. For an automaton type β (e.g., DBW) and an automaton \mathcal{A} , we say that \mathcal{A} is β -realizable if there is a β -automaton equivalent to \mathcal{A} .

Let $\mathcal{A} = \langle \mathcal{A}, Q, Q_0, \delta, \alpha \rangle$ be an automaton. For an acceptance-condition class γ (e.g., Büchi), we say that \mathcal{A} is γ -type if \mathcal{A} has an equivalent γ automaton with the same structure as \mathcal{A} [5]. That is, there is an automaton $\mathcal{A}' = \langle \Sigma, Q, Q_0, \delta, \alpha' \rangle$ such that α' is an acceptance condition of the class γ and $L(\mathcal{A}') = L(\mathcal{A})$.

2.2 Good-For-Games Automata

An automaton $\mathcal{A} = \langle \Sigma, Q, Q_0, \delta, \alpha \rangle$ is good for games (GFG, for short) if there is a strategy $g \colon \Sigma^* \to Q$, such that for every word $w = a_1 \cdot a_2 \cdots \in \Sigma^{\omega}$, the sequence $g(w) = g(\epsilon)$, $g(a_1)$, $g(a_1 \cdot a_2)$,... is a run of \mathcal{A} on w, and whenever $w \in L(\mathcal{A})$, then g(w) is accepting. We then say that g witnesses \mathcal{A} 's GFGness.

It is known [2] that if \mathcal{A} is GFG, then its GFGness can be witnessed by a finite-state strategy, thus one in which for every state $q \in Q$, the set of words $g^{-1}(q)$ is regular. Finite-state strategies can be modeled by transducers. Given sets I and O of input and output letters, an (I/O)-transducer is a tuple $\mathcal{T} = \langle I, O, M, m_0, \rho, \tau \rangle$, where M is a finite set of states, to which we refer as memories, $m_0 \in M$ is an $initial\ memory$, $\rho \colon M \times I \to M$ is a deterministic transition function, to which we refer as the $memory\ update\ function$, and $\tau \colon M \to O$ is an output function that assigns a letter in O to each memory. The transducer \mathcal{T} generates a strategy $g_{\mathcal{T}} \colon I^* \to O$, obtained by following ρ and τ in the expected way: we first extend ρ to words in I^* by setting $\rho(\epsilon) = m_0$ and $\rho(u \cdot a) = \rho(\rho(u), a)$, and then define $g_{\mathcal{T}}(u) = \tau(\rho(u))$.

Consider a GFG automaton $\mathcal{A}=\langle \Sigma,Q,Q_0,\delta,\alpha\rangle$, and let $g=\langle \Sigma,Q,M,m_0,\rho,\tau\rangle$ be a finite-state (Σ/Q) -transducer that generates a strategy $g\colon \Sigma^*\to Q$ that witnesses \mathcal{A} 's GFGness (we abuse notations and use g to denote both the transducer and the strategy it generates). Consider a state $q\in Q$. When $\tau(m)=q$, we say that m is a memory of q. We denote by \mathcal{A}_g the (deterministic) automaton that models the operation of \mathcal{A} when it follows g. Thus, $\mathcal{A}_g=\langle \Sigma,M,m_0,\rho,\alpha_g\rangle$, where the acceptance condition α_g is obtained from α by replacing each set $F\subseteq Q$ that approximates in α (e.g. accepting states, rejecting states, set in a Rabin or Streett pair, etc) by the set $F_g=\{m\mid \tau(m)\in F\}$. Thus, $F_g\subseteq M$ contains the memories of F's states. For a state q of \mathcal{A} , a path π of \mathcal{A}_g is q-exclusive accepting if π is accepting, and $\inf(\pi)\setminus\{m\mid m\text{ is a memory of }q\}$ is not accepting.

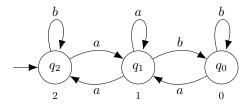
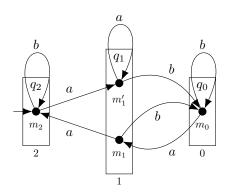


Figure 1 A weakly tight GFG-NPW A_0 . The numbers below the states describe their priorities.



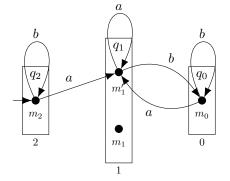


Figure 2 A strategy witnessing the GFGness of the automaton A_0 , depicted in Figure 1.

Figure 3 A strategy witnessing the tightness of a sub-automaton of A_0 .

▶ **Example 1.** Consider the NPW \mathcal{A}_0 appearing in Figure 1. We claim that \mathcal{A}_0 is a GFG-NPW that recognizes the language $L_0 = \{w \in \{a,b\}^{\omega} \mid \text{there are infinitely many } b$'s in w}.

Proof sketch. If a word w contains only finitely many b's then A_0 rejects w, as in all the runs of A_0 on w, the lowest priority appearing infinitely often is 1. Therefore, $L(A_0) \subseteq L_0$.

We turn to describe a strategy $g: \{a, b\}^* \to Q$ with which \mathcal{A}_0 accepts all words in L_0 . The only nondeterminism in \mathcal{A}_0 is when reading the letter a in the state q_1 . Thus, we have to describe g only for words that reach q_1 and continue with an a. In that case, the strategy g moves to the state q_2 , if the previous state is q_0 , and to the state q_1 , otherwise. Figure 2 describes a (Σ/Q) -transducer that generates g. The rectangles denote the states of \mathcal{A}_0 , while the dots are their g-memories. The numbers below the rectangles describe the priorities of the respective states of \mathcal{A}_0 . It is easy to check that if $w \in L_0$ (i.e. w contains infinitely many b's) then \mathcal{A}_{0g} accepts w.

The following lemma generalizes known residual properties of GFG automata (c.f., [6]).

- ▶ **Lemma 2.** Consider a GFG automaton $\mathcal{A} = \langle \Sigma, Q, Q_0, \delta, \alpha \rangle$ and let $g = \langle \Sigma, Q, M, m_0, \rho, \tau \rangle$ be a strategy witnessing its GFGness.
- (1) For every state $q \in Q$ and memory $m \in M$ of q that is reachable in A_g , we have that $L(A_g^m) = L(A_g^q)$.
- (2) For every memories $m, m' \in M$ that are reachable in A_g with $\tau(m) = \tau(m')$, we have that $L(A_g^m) = L(A_g^{m'})$.

A finite $path \ \pi = q_0, \ldots, q_k$ in \mathcal{A} is a sequence of states such that for $i = 0, \ldots, k-1$ we have $q_{i+1} \in \delta(q_i, a_i)$ for some $a_i \in \Sigma$. A path is a *cycle* if $q_0 = q_k$. Each path π induces a set $states(\pi) = \{q_0, \ldots, q_k\}$ of states in Q. A set S of finite paths then induces the set $states(S) = \bigcup_{\pi \in S} states(\pi)$. For a set P of finite paths, a *combination of paths from* P is a set states(S) for some nonempty $S \subseteq P$.

Consider a strategy $g = \langle \Sigma, Q, M, m_0, \rho, \tau \rangle$. We say that a transition $\langle q, a, q' \rangle$ of \mathcal{A} is used by g if there is a word $u \in \Sigma^*$ and a letter $a \in \Sigma$ such that q = g(u) and $q' = g(u \cdot a)$. Consider two memories $m \neq m' \in M$ with $\tau(m) = \tau(m')$. Let $P_{m' \to m}$ be the set of paths of \mathcal{A}_g from m' to m. We say that m is replaceable by m' if $P_{m' \to m}$ is empty or all combinations of paths from $P_{m' \to m}$ are accepting.

We say that \mathcal{A} is tight with respect to g if all the transitions of \mathcal{A} are used in g, and for all memories $m \neq m' \in M$ with $\tau(m) = \tau(m')$, we have that m is not replaceable by m'. Intuitively, the latter condition implies that both m and m' are required in g, as an attempt to merge them strictly reduces the language of \mathcal{A}_g . When only the first condition holds, namely when all the transitions of \mathcal{A} are used in g, we say that \mathcal{A} is weakly tight with respect to g. When a Rabin automaton \mathcal{A} is tight with respect to g, and in addition for every state g that appears in some good set of \mathcal{A} 's acceptance condition, there is a g-exclusive accepting cycle in \mathcal{A}_g , we say that \mathcal{A} is strongly tight with respect to g. Then, \mathcal{A} is (weakly, strongly) tight if it is (weakly, strongly) tight with respect to some strategy.

▶ **Example 3.** The GFG-NPW A_0 from Example 1 is weakly tight and is not tight with respect to the strategy g. Indeed, while all the transitions in A_0 are used in g, the memory m_1 is replaceable by m'_1 , as all combinations of paths from m'_1 to m_1 are accepting. \blacktriangleleft

The following lemma formalizes the intuition that every GFG automaton can indeed be restricted to its tight part, by removing redundant transitions and memories. Further, every tight Rabin GFG automaton has an equivalent strongly tight automaton over the same structure.

- ▶ **Lemma 4.** For every GFG automaton \mathcal{A} there exists an equivalent tight GFG automaton \mathcal{A}' . Moreover, \mathcal{A}' is defined on a substructure of \mathcal{A} .
- ▶ Lemma 5. For every tight Rabin GFG automaton, there exists an equivalent strongly tight Rabin GFG automaton over the same structure.
- ▶ Example 6. In Figure 3 we describe a strategy g' that witnesses the tightness of a GFG-NPW on a substructure of the GFG-NPW \mathcal{A} from Example 1. The strategy g' is obtained from g by following the procedure described in the proof of Lemma 4: all the transitions to m_1 are redirected to m'_1 . This causes the transition (q_1, a, q_2) that was used by the memory m_1 not to be used, and it is removed.

A special case of GFG automata are those who are determinizable by pruning (or shortly DetByP) — there exists a state $q_0 \in Q_0$ and a function $\delta' \colon Q \times \Sigma \to Q$ that for every state q and letter a satisfies $\delta'(q, a) \in \delta(q, a)$ such that $\mathcal{A}' = \langle \Sigma, Q, q_0, \delta', \alpha \rangle$ is a deterministic automaton recognizing the language $L(\mathcal{A})$.

3 Typeness Does Not Hold for Unambiguous Automata

As noted in [7], it is easy to see that typeness does not hold for nondeterministic automata: there exists an NRW that recognizes an NBW-realizable language, yet does not have an equivalent NBW on the same structure. Indeed, since all ω -regular languages are NBW-realizable, typeness in the nondeterministic setting would imply a translation of all NRWs to NBWs on the same structure, and we know that such a translation may involve a blow-up linear in the index of the NRW [17]. Even for Streett and co-Büchi automata, where the restriction to NCW-realizable languages amounts to a restriction to DCW-realizable languages, typeness does not hold.

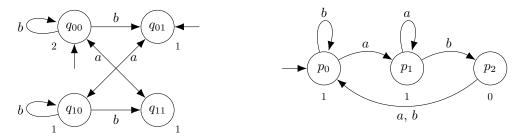


Figure 4 \mathcal{A}_1 : An unambiguous NPW that is DBW-realizable yet is not Büchi-type.

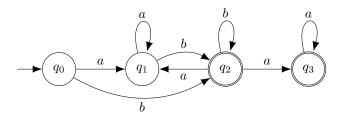


Figure 5 A_2 : An unambiguous NBW that is DCW-realizable yet is not co-Büchi-type.

In this section we strengthen the relation between typeness and determinism and show that typeness does not hold for nondeterministic automata even when they recognize a DBW-realizable language and, moreover, when they are unambiguous. Also, we prove the non-typeness results for NPWs, thus they apply to both Rabin and Streett automata.

▶ Example 7. Unambiguous NPWs are not Büchi-type with respect to DBW-realizable languages: The automaton \mathcal{A}_1 depicted in Figure 4 is unambiguous and recognizes a DBW-realizable language, yet \mathcal{A}_1 is not Büchi-type. Moreover, we cannot prune transitions from \mathcal{A}_1 and obtain an equivalent Büchi-type NPW.

The dual case of unambiguous NPWs that are not co-Büchi-type with respect to DCW-realizable languages follows from the results of [7], and we give it here for completeness, adding the observation that the automaton described there cannot be pruned to an equivalent co-Büchi-type NPW.

▶ Example 8. [7] Unambiguous NPWs (and even NBWs) are not co-Büchi-type with respect to DCW-realizable languages: The NBW A_2 depicted in Figure 5 is unambiguous, and recognizes a DCW-realizable language, yet A_2 is not co-Büchi-type. Moreover, we cannot prune transitions from A_2 for obtaining an equivalent co-Büchi-type NPW.

We conclude this section with the following rather simple proposition, showing that automata that are both unambiguous and GFG are essentially deterministic. Essentially, it follows from the fact that by restricting an unambiguous GFG automaton \mathcal{A} to reachable and nonempty states, we obtain, by pruning, a deterministic automaton, which is clearly equivalent to \mathcal{A} .

▶ **Proposition 9.** *Unambiguous GFG automata are DetByP.*

4 Co-Büchi Typeness for GFG-NSWs

In this section we study typeness for GFG-NSWs and show that, as is the case with deterministic automata, tight GFG-NSWs are co-Büchi-type. On a more technical level, the

proof of Theorem 10 only requires the GFG automata to be weakly tight (rather than fully tight), implying that Theorem 10 can be strengthened in accordance. This fact is considered in Section 5, where the typeness of GFG-NRWs is shown to require full tightness.

▶ Theorem 10. Tight GFG-NSWs are co-Büchi-type: Every tight GFG-NSW that recognizes a GFG-NCW-realizable language has an equivalent GFG-NCW on the same structure.

Proof sketch. Given a GFG-NSW \mathcal{A} and a strategy g that witnesses its GFGness, we change \mathcal{A} into an NCW \mathcal{A}' by defining the co-Büchi acceptance condition α' to include the states all of whose g-memories only belong to rejecting cycles in \mathcal{A}_g .

We then prove that L(A) = L(A') and that A' is indeed GFG. (Furthermore, we show that the original strategy g also witnesses the GFGness of A'.) The proof goes by induction, iterating over all states g of A, and gradually changing the acceptance condition until it becomes a co-Büchi condition. We show that at each step of the induction, the resulting automaton is still a GFG-NSW that recognizes the original language.

We start the induction with the original GFG-NSW \mathcal{A} , and add to its acceptance condition a new empty Streett pair, namely (\emptyset, \emptyset) . Along the induction, handling a state q, we remove q from all the original "bad" sets (namely the left components) of the acceptance condition, and in the case that $q \in \alpha'$, we add it to the bad set of the new acceptance pair. Observe that at the end of the induction, the acceptance condition consists of a single Streett pair, in which α' is the bad set and \emptyset is the good set. Thus, it is in fact the NCW \mathcal{A}' .

The tricky part of the induction step is when the considered state q does not belong to α' . In this case, removing it from the bad sets might enlarge the language of the automaton. To prove that the language is not altered, we take advantage of the fact that there exists a deterministic co-Büchi automaton \mathcal{D} equivalent to \mathcal{A} , and provide a pumping scheme that proceeds along the cycles of \mathcal{A} and \mathcal{D} .

Analyzing these cycles, we use the (weak) tightness of \mathcal{A} , in order to use Lemma 2—the pumped cycles might go through states of \mathcal{A} that were not originally visited. Yet, due to Lemma 2, we may link the residual languages of the originally visited states with that of the newly visited ones.

The following example shows that the weak tightness requirement cannot be omitted, even when the GFG-NSW is actually a GFG-NBW.

▶ **Example 11.** The automaton A_3 depicted in Figure 7 is GFG-NBW and recognizes a GFG-NCW-realizable language, yet A_3 has no equivalent NCW on the same structure.

5 Büchi Typeness for GFG-NRWs

Studying typeness for deterministic automata, one can use the dualities between the Büchi and co-Büchi, as well as the Rabin and Streett conditions, in order to relate the Büchitypeness of DRWs with the co-Büchi typeness of DSWs. In the nondeterministic setting, we cannot apply duality considerations, as by dualizing a nondeterministic automaton, we obtain a universal one. As we shall see in this section, our inability to use dualization considerations is not only technical. There is an inherent difference between the co-Büchi typeness of GFG-NSWs studied in Section 4, and the Büchi typeness of GFG-NRWs, which we study here. We first show that while the proof of Theorem 10 only requires weak tightness, Büchi typeness requires full tightness.

The following example shows that tightness is necessary already for GFG-NCW that are GFG-NBW-realizable.

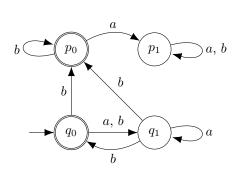


Figure 6 \mathcal{A}_4 : A weakly tight GFG-NCW that is GFG-NBW-realizable yet is not Büchitype.

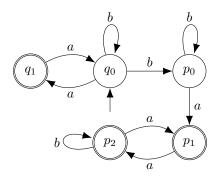


Figure 7 A_3 : A GFG-NBW that is GFG-NCW-realizable yet is not co-Büchi-type.

Example 12. The automaton A_4 depicted in Figure 6 is a weakly tight GFG-NCW that recognizes a GFG-NBW-realizable language, yet A_4 has no equivalent GFG-NBW on the same structure.

We now proceed to our main positive result, obtaining the typeness of GFG-NRWs.

▶ Theorem 13. Tight GFG-NRWs are Büchi-type: Every tight GFG-NRW that recognizes a GFG-NBW-realizable language has an equivalent GFG-NBW on the same structure.

Proof sketch. Consider a tight GFG-NRW \mathcal{A} that recognizes a GFG-NBW-realizable language. Let q be a strategy that witnesses \mathcal{A} 's GFGness and with respect to which \mathcal{A} is tight. By Lemma 5, we have a GFG Rabin automaton \mathcal{A}' over the structure of \mathcal{A} that is strongly tight with respect to g. We define an NBW \mathcal{B} on top of \mathcal{A} 's structure, setting its accepting states to be all the states that appear in "good" sets of \mathcal{A}' (namely in the right components of the Rabin accepting pairs).

Clearly, $L(\mathcal{A}') \subseteq L(\mathcal{B})$, as \mathcal{B} 's condition only requires the "good" part of \mathcal{A}' 's condition, without requiring to visit finitely often in a corresponding "bad" set. We should thus prove that $L(\mathcal{B}) \subseteq L(\mathcal{A}')$ and that \mathcal{B} is GFG. Once proving the language equivalence, \mathcal{B} 's GFGness is straight forward, as the strategy g witnesses it. The language equivalence, however, is not at all straightforward.

In order to prove that $L(\mathcal{B}) \subseteq L(\mathcal{A}')$, we analyze the cycles of \mathcal{A}' and of \mathcal{A}'_q . The proof goes along the following steps:

- We start with showing that a memory of a state q cannot belong to both a q-exclusive accepting cycle and a rejecting cycle. In order to prove that, we take advantage of the fact that there is a DBW \mathcal{D} equivalent to \mathcal{A}' , and provide a pumping argument concerning the cycles of \mathcal{A}' and \mathcal{D} .
- By the above and the strong tightness of \mathcal{A}' , we show that every state q of \mathcal{A}' that appears in some good set has a single memory, all the cycles of \mathcal{A}'_q that include q are accepting, and at least one of them is q-exclusive. Observe that this implies the language containment $L(\mathcal{A}'_a) \subseteq L(\mathcal{B})$. Yet, it does not guarantee that $L(\mathcal{A}') \subseteq L(\mathcal{B})$, as there might be some rejecting cycle of \mathcal{A}' that \mathcal{A}'_q does not use, which becomes accepting by our changes to the acceptance condition.
- For precluding the aforementioned concern and concluding our proof, we show that every state q of \mathcal{A}' that appears in some good set does not belong to a rejecting cycle. We

prove it by applying a maximality argument on paths that the strategy g exhausts along a hypothetical rejecting cycle of \mathcal{A}' that includes q.

The following result follows directly from Lemma 4, Theorem 13, and the determinization procedure for Büchi GFG automata from [6].

▶ Corollary 14. Every GFG-NRW with n states that recognizes a DBW-realizable language has an equivalent DBW with at most $O(n^2)$ states.

6 Weak Typeness for GFG Automata

A Büchi automaton \mathcal{A} is weak [13] if for each strongly connected component C of \mathcal{A} , either $C \subseteq \alpha$ (in which case we say that C is an accepting component) or $C \cap \alpha = \emptyset$ (in which case we say that C is a rejecting component). Note that a weak automaton can be viewed as both a Büchi and a co-Büchi automaton, as a run of \mathcal{A} visits α infinitely often iff it gets trapped in an accepting component iff it visits states in $Q \setminus \alpha$ only finitely often. We use NWW and DWW to denote nondeterministic and deterministic weak word automata, respectively.

We show in this section that all GFG automata are type with respect to the weak acceptance condition. We provide the theorem with respect to GFG-NCWs, from which we can easily deduce it, by our previous typeness results, also for the other types.

▶ **Theorem 15.** Tight GFG-NCWs are weak-type: every tight GFG-NCW that recognizes a GFG-NWW-realizable language has an equivalent GFG-NWW on the same structure.

Proof sketch. Consider a tight GFG-NCW \mathcal{A} that recognizes a GFG-NWW-realizable language. Let S be the set of rejecting states of \mathcal{A} and let g be a strategy witnessing \mathcal{A} 's tight GFGness. Let S' be the union of S and all the states g of \mathcal{A} for which no g-memory g has an accepting cycle in \mathcal{A}_g . Let \mathcal{A}' be the automaton \mathcal{A} with the co-Büchi condition given by S'. Analyzing the cycles of \mathcal{A}' , we show that it is a GFG-NWW equivalent to \mathcal{A} .

Consider now a GFG-NSW \mathcal{A} that is GFG-NWW-realizable. Notice that it is obviously also GFG-NBW-realizable. Hence, by Theorem 10, there is a GFG-NCW on \mathcal{A} 's structure, and by Theorem 15 also a GFG-NWW. The cases of a GFG-NPW and a GFG-NBW obviously follow, since they are special cases of GFG-NSWs. As for a GFG-NRW \mathcal{A} that is GFG-NWW-realizable, notice that it is obviously also GFG-NBW-realizable. Hence, by Theorem 13, there is a GFG-NBW on \mathcal{A} 's structure, and by Theorem 15 also a GFG-NWW.

▶ Corollary 16. Tight GFG-NSWs and GFG-NRWs are weak-type: every tight GFG-NSW and GFG-NRW that recognizes a GFG-NWW-realizable language has an equivalent GFG-NWW on the same structure.

Next, we show that GFG-NWWs are DetByP, generalizing a folklore result about safe and co-safe GFG automata.

▶ Theorem 17. *GFG-NWWs are DetByP.*

Proof sketch. Consider a GFG-NWW \mathcal{A} with accepting set α , whose GFGness is witnessed by a strategy g. By arguments analogous to those made in the proof of Theorem 13, a state $q \in \alpha$ has only one g-memory, and is therefore already deterministic.

The interesting part concerns a state $q \notin \alpha$ that has at least two g-memories m and m'. Let g' be the strategy obtained by removing m' from g and redirecting transitions to m' into m. We claim that $L(\mathcal{A}_g) = L(\mathcal{A}_{g'})$, from which it follows by induction that the number of memories of each state of \mathcal{A} can be reduced to 1. We prove the claim by induction on the strongly connected components of \mathcal{A} and by inductively applying Lemma 2.

By combining the above results, we obtain the following corollary.

▶ Corollary 18. Every GFG-NSW and GFG-NRW that recognizes a GFG-NWW-realizable language is DetByP.

7 Consequences

GFG automata provide an interesting formalism in between deterministic and nondeterministic automata. Their translation to deterministic automata is immediate for the weak condition (Theorem 17), polynomial for the Büchi condition [6], and exponential for the co-Büchi, parity, Rabin, and Streett conditions [6]. They have the same typeness behavior as deterministic automata, summarized in Table 1. The positive results of Table 1 follow from our theorems in Sections 4, 5, and 6. The negative results follow from corresponding counterexamples with deterministic automata [5, 7]. Considering the complementation of GFG automata, they lie in between the deterministic and nondeterministic settings, as shown in Table 2. As for the translation of LTL formulas to GFG automata, it is doubly exponential, like the translation to deterministic automata (Corollary 21 below).

Complementation

In the deterministic setting, Rabin and Streett automata are dual: complementing a DRW into a DSW, and vice versa, is simply done by switching between the two acceptance conditions on top of the same structure. This is not the case with GFG automata. We show below that complementing a GFG-NSW, and even a GFG-NCW, into a GFG-NRW involves an exponential state blow-up. Essentially, it follows from the Büchi-typeness of GFG-NRWs (Theorem 13) and the fact that while determinization of GFG-NBWs involves only a quadratic blow-up, determinization of GFG-NCWs involves an exponential one [6].

▶ Corollary 19. The complementation of a GFG-NCW into a GFG-NRW involves a $2^{\Omega(n)}$ state blow-up.

Using our typeness results, we get an almost complete picture on complementation of GFG automata.

▶ **Theorem 20.** The state blow-up involved in the complementation of GFG automata is as summarized in Table 2.

Proof.

- From weak and Büchi. A GFG-NBW \mathcal{A} with n states has an equivalent DBW \mathcal{D} with up to n^2 states [6], on which structure there is a DCW $\overline{\mathcal{D}}$ for the complement language. Notice that $\overline{\mathcal{D}}$ is also a GFG-NCW, GFG-NPW, GFG-NRW, and GFG-NSW. Now, if there is a GFG-NBW equivalent to $\overline{\mathcal{D}}$, then $\overline{\mathcal{D}}$ is DWW-recognizable, and, by Theorem 15, there is a GFG-NWW on a substructure of $\overline{\mathcal{D}}$.
- From co-Büchi. By Corollary 19, we have the exponential state blow-up in the complementation to GFG-NPW and GFG-NRW automata. Since the complement of a co-Büchi-recognizable language is DBW-recognizable, we get an exponential state blow-up also to GFG-NBW.
- To weak and co-Büchi. Consider a GFG-NCW, GFG-NPW, or GFG-NRW \mathcal{A} with n states that can be complemented into a GFG-NCW \mathcal{C} . Then the language of \mathcal{A} is GFG-NBW recognizable. Thus, by Theorem 13, there is a GFG-NBW equivalent to \mathcal{A} with up to n states. Hence, by case (1), there is a GFG-NCW for the complement of \mathcal{A} with up to n^2 states.

Table 1 Typeness in translations between GFG automata. (Y=Yes; N=No.)

Type To From	W	В	С	Р	R	S			
Weak									
Büchi									
Co-Büchi	Yes								
Parity									
Rabin	No			Y	N				
Streett		N	Y	No		Y			

Table 2 The state blow-up involved in the complementation of GFG automata.

Comp. To From	$\overline{\mathrm{W}}$	$\overline{\mathbf{C}}$	$\overline{\mathrm{B}}$	P	\overline{R}	$\overline{\mathrm{S}}$
Weak						
Büchi	Po					
Co-Büchi						
Parity	Exp					?
Rabin				Ехр		
Streett						

- From Streett to weak. Consider a GFG-NSW \mathcal{A} that can be complemented to a GFG-NWW. Then the language of \mathcal{A} is DWW-recognizable. Thus, by Theorems 10 and 15, there is a GFG-NWW on a substructure of \mathcal{A} , and we are back in case (1).
- From Streett to co-Büchi. Given a DRW \mathcal{A} that is NCW realizable, one can translate it to an equivalent NCW by first dualizing \mathcal{A} into a DSW $\overline{\mathcal{A}}$ for the complement language, and then complementing $\overline{\mathcal{A}}$ into a GFG-NCW \mathcal{C} . Since dualizing a DRW into a DSW is done with no state blowup and the translation of DRWs to NCWs might involve an exponential state blowup [1], so does the complementation of GFG-NSW to GFG-NCWs.
- From Streett to Streett. Analogous to the above case of Streett to co-Büchi, due to the exponential state blowup in the translation of DRWs to NSWs [1]. ◀

Translating LTL formulas to GFG Automata

Recall that GFG-NCWs are exponentially more succinct than DCWs [6], suggesting they do have some power of nondeterministic automata. A natural question is whether one can come up with an exponential translation of LTL formulas to GFG automata, in particular when attention is restricted to LTL formulas that are DCW-realizable. We complete this section with a negative answer, providing another evidence for the deterministic nature of GFG automata. This result is based on the fact that the language with which the doubly-exponential lower bound of the translation of LTL to DBW in [9] is proven is bounded (that is, it is both safe and co-safe). It means that by Corollary 18, any GFG-NSW for it would be DetByP, contradicting the doubly-exponential lower bound.

▶ Corollary 21. The translation of DCW-realizable LTL formulas into GFG-NSW is doubly exponential.

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